

Alberto Rodriguez

Associate Professor

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PROFESSIONAL APPOINTMENTS

Massachusetts Institute of Technology

2020 - present Class of 1957 Career Development Professor
2019 - present Associate Professor without tenure (AWOT), Department of Mechanical Engineering
2016 - 2019 Walter Henry Gale (1929) Career Development Professor
2014 - 2018 Assistant Professor, Department of Mechanical Engineering

Other

Summer 2009 Research Intern, ABB US Corporate Research Center, Windsor, CT, USA
2004 - 2006 Research Assistant, UPC, Department of Automatic Control, ESAII, Barcelona, Spain

EDUCATION

2014 Postdoc, MIT (advised by Prof. Russ Tedrake)
2013 PhD Robotics, CMU, Thesis "Shape for Contact" (advised by Prof. Matthew Mason)
2006 Degree in Telecommunications Engineering, UPC
2005 Degree in Mathematics, UPC

AWARDS AND HONORS

Paper Awards

2020 RSS [Best Paper Award Finalist](#)
Cable Manipulation with a Tactile-Reactive Gripper

2020 ICRA [Best Manipulation Paper Award Finalist](#)
Tactile Dexterity: Manipulation Primitives with Tactile Feedback

2019 RSS [Best Systems Paper Award](#)
TossingBot: Learning to Throw Arbitrary Objects with Residual Physics

2018 IROS [Best Cognitive Paper Award](#)
Augmenting Physical Simulators with Stochastic Neural Networks: Case Study of Planar Pushing and Bouncing

2018 IROS [Best Cognitive Paper Award Finalist](#)
Learning Synergies between Pushing and Grasping with Self-Supervised Deep Reinforcement Learning

2018 Amazon [Best Systems Paper Award in Manipulation](#)
Robotic Pick-And-Place of Novel Objects in Clutter with Multi-Affordance Grasping and Cross-Domain Image Matching

2018 Amazon [Best Technical Paper Award in Manipulation Finalist](#)
GelSlim: A High-Resolution, Compact, Robust, and Calibrated Tactile-sensing Finger

2018 RSS [Best Student Paper Award](#)
In-Hand Manipulation via Motion Cones

2016 IROS [Best Paper Award Finalist](#)
More than a Million Ways to be Pushed: A High-Fidelity Experimental Data Set of Planar Pushing

2014 ICRA [Best Video Award Finalist](#)
Regrasping Objects with Extrinsic Dexterity

2013 ICRA [Best Student Paper Award](#)
Effector Form Design for 1DOF Planar Actuation

2011 RSS [Best Student Paper Award](#)
From Caging to Grasping

Other Awards

- 2020 IEEE Early Academic Career Award in Robotics and Automation
"For contributions to dexterous robot manipulation".
- 2020 Class of 1957 Career Development Professorship.
"This professorship recognizes innovative and imaginative teaching".
- 2020 Google Faculty Research Award.
- 2020-18 Amazon Faculty Research Award 2020, 2019, 2018.
- 2017 Amazon Robotics Challenge 2017, Stowing task, 1st place.
- 2016 Walter Henry Gale (1929) Career Development Professorship.
- 2016 Amazon Picking Challenge 2016, 3rd and 4th place.
- 2015 Amazon Picking Challenge 2015, 2nd place.

LEADERSHIP AND SERVICE ACTIVITIES**Massachusetts Institute of Technology**

- 2021 MIT, MechE, General Faculty Search committee.
- 2020 - present MIT, MechE, Committee Strategic Integration of Data Science in Mech. Eng.
- 2020 MIT, Team 2020, Evaluating MIT's options for Fall semester in light of COVID-19.
- 2020 - present MIT, Housing, COVID-19 Policies committee.
- 2019 MIT, Housing, Policies committee.
- 2018 - present MIT, Robotics, Lead MIT Robotics Seminar and fundraising for MIT Robotics.
- 2016 - present MIT, Housing, Associate Head of House in graduate dorm Sydney-Pacific.
- 2013 - present MIT, MechE, Graduate Admissions Committee.
- 2016 MIT, MechE, Controls and Dynamics Curriculum Revision Committee.

Robotics Community

- 2021 - present CESAR: IEEE Committee to Explore Synergies in Automation and Robotics
- 2021 - present RSS Sponsorship chair
- 2020 - present Co-created "Robotics Today" (<http://roboticstoday.github.io>)
 Open virtual series of technical talks in robotics.
- 2020 - 2019 RSS Area chair for Manipulation
- 2016 Co-editor IEEE RAM "Open Source and Widely-Disseminated Robot Hardware".
- Program committee at ISRR 2019, RSS 2018-14, WAFR 2018-16 and ISER 2014.

Workshop Organization

- 2021 RSS 2021 "Feedback in Manipulation: Industrial/Academic Perspectives" (under review)
- 2018 ICRA 2018 "Advances in Robotic Warehouse Automation"
- 2017 RSS 2017 "Empirically Data-driven Robotic Manipulation"
- 2017 ICRA 2017 "Warehouse Picking Automation Workshop 2017: Solutions, Experience, Learnings and Outlook of the Amazon Picking Challenge"
- 2016 CASE 2016 "Automation for Warehouse Logistics"
- 2015 NSF "Locomotion and Manipulation: Why the Great Divide?"
- 2013 ICRA 2013 "Caging and its Applications in Grasping/Multi-agent Cooperation."
- 2013 RSS 2013 "Common Platforms in Robotic Manipulation."

TEACHING EXPERIENCE

- 2021 Spring 2.003 Dynamics and Controls I - lead instructor
- 2020 Fall 2.003 Dynamics and Controls I - lead instructor
- 2020 Spring 2.003 Dynamics and Controls I - lead instructor
- 2019 Spring 2.003 Dynamics and Controls I - lead instructor
- 2018 Fall 2.003 Dynamics and Controls I - lead instructor
- 2018 Spring 2.003 Dynamics and Controls I - lead instructor
- 2017 Fall 2.003 Dynamics and Controls I
- 2017 Spring 2.003 Dynamics and Controls I

2016 Fall	2.12 Introduction to Robotics - co-lead instructor
2016 Spring	2.003 Dynamics and Controls I
2015 Fall	2.003 Dynamics and Controls I - co-lead instructor
2015 Spring	2.003 Dynamics and Controls I - co-lead instructor
2014 Fall	2.003 Dynamics and Controls I

INTELLECTUAL PROPERTY

2020 Oct	Patent (provisional) “PnuGrip: An Active Two-Phase Gripper” Filing Date: October 6, 2020, Application Number: 63/088,113
2019 Nov	Patent (provisional) “Tactile Dexterity and Control” Filing Date: November 15, 2019, Application Number: 62/935,676
2018 Aug	Patent “Shape-Shifting Fingers for Robotic Grippers” Publication numbers: US-2020-0055197-A1, WO 2020/041116
2018 Aug	Patent “Robotic Manipulation of Objects for Grip Adjustment” Publication numbers: US-2020-0055680-A1, WO 2020/041117
2018 Aug	Patent “Robotic Manipulation of Objects Using External Contacts” Publication numbers: US-2020-0055152-A1, WO 2020/041120
2017 Feb	Patent “Two-Phase Gripper to Reorient and Grasp” Publication number: US20170036354 A1
2014 Nov	Patent “Method and Apparatus for Using Post Assembly Process Interaction Signatures to Detect Assembly Failures” Publication numbers: WO2014160760 A3, CN105229548 A

PUBLICATIONS UNDER REVIEW

- [J19] 2021 IJRR *Cable Manipulation with a Tactile-Reactive Gripper*
She Y., S. Wang, S. Dong, N. Sunil, A. Rodriguez and E. Adelson
- [J18] 2021 TRO *Tactile Dexterity: Manipulation Primitives with Tactile Feedback*
Hogan, F., A. Simeonov, J. Ballester, S. Dong and A. Rodriguez
- [C67] 2021 IROS *iNeRF: Inverting Neural Radiance Fields for Pose Estimation*
Yen-Chen L., P. Florence, J. Barron, A. Rodriguez, P. Isola, T. Lin
- [C68] 2021 IROS *GelSlim 3.0: High-Resolution Measurement of Shape, Force and Slip in a Compact Tactile-Sensing Finger*
Taylor I., S. Dong and A. Rodriguez
- [C69] 2021 IROS *Inference and Planning with Virtual and Physical Constraints for Object Manipulation*
Loula J., K. Allen, A. Rodriguez, J. Tenenbaum and N. Fazeli

PUBLICATIONS

Edited Books

- [B1] 2020 Springer *Advances on Robot Item Picking. Applications in Warehousing & E-Commerce Fulfillment*
Causo A., J. Durham, K. Hauser and A. Rodriguez

Refereed Journal Papers

- [J17] 2020 PNAS *On the Use of Modeling and Simulation in Robotics: Opportunities, Challenges, and Suggestions for Moving Forward*
Choi, H., C. Crump, C. Duriez, A. Elmquist, G. Hager, D. Han, F. Hearl, J. Hodgins, A. Jain, F. Leve, C. Li, F. Meier, D. Negrut, L. Righetti, A. Rodriguez, J. Tan and J. Trinkle
- [J16] 2020 TRO *TossingBot: Learning to Throw Arbitrary Objects with Residual Physics*
Zeng, A., S. Song, J. Lee, A. Rodriguez and T. Funkhouser
- [J15] 2020 IJRR *Reactive Planar Manipulation with Hybrid Model Predictive Control*
Hogan, F. and A. Rodriguez

- [J14] 2019 A. Rob. *What are the Important Technologies for Bin Picking? Technology Analysis of Robots in Competitions based on a Set of Performance Metrics* (Advanced Robotics)
Fujita M., Y. Domae, A. Noda, G. Garcia Ricardez, T. Nagatani, A. Zeng, S. Song, A. Rodriguez, A. Causo, I.M. Chen, and T. Ogasawara
- [J13] 2019 IJRR *Planar In-Hand Manipulation via Motion Cones*
Chavan-Dafle, N., R. Holladay and A. Rodriguez
- [J12] 2019 IJRR *Robotic Pick-and-Place of Novel Objects in Clutter with Multi-Affordance Grasping and Cross-Domain Image Matching*
Zeng, A., S. Song, K.-T. Yu, E. Donlon, F. Hogan, M. Bauza, D. Ma, O. Taylor, M. Liu, E. Romo, N. Fazeli, F. Alet, N. Chavan-Dafle, R. Holladay, I. Morona, P. Nair, D. Green, I. Taylor, W. Liu, T. Funkhouser and A. Rodriguez
- [J11] 2019 Science *See, feel, act: Hierarchical learning for complex manipulation skills with multisensory fusion* (Science Robotics)
Fazeli, N., M. Oller, J. Wu, , Z. Wu, J. Tenenbaum and A. Rodriguez.
- [J10] 2018 TASE *Open Discussion of Robot Grasping Benchmarks, Protocols, and Metrics (Editorial)*
Mahler, J., R. Platt, A. Rodriguez, M. Ciocarlie, A. Dollar, R. Detry, M. A. Roa, H. Yanco, A. Norton, J. Falco, K. van Wyk, E. Messina, J. Leitner, D. Morrison, M. Mason, O. Brock, L. Odhner, A. Kurenkov, M. Matl, and K. Goldberg
- [J9] 2018 AURO *Optimal Shape and Motion Planning for Dynamic Planar Manipulation*
Taylor, O. and A. Rodriguez
- [J8] 2018 TASE *Analysis and Observations from the First Amazon Picking Challenge*
Correll, N., K. Bekris, D. Berenson, O. Brock, A. Causo, K. Hauser, K. Okada, A. Rodriguez, J. Romano and P. Wurman
- [J7] 2018 RA-L *Friction Variability in Planar Pushing Data: Anisotropic Friction and Data-collection*
Ma, D. and A. Rodriguez
- [J6] 2017 IJRR *Parameter and Contact Force Estimation of Planar Rigid-Bodies Undergoing Frictional Contact*
Fazeli, N., R. Kolbert, R. Tedrake and A. Rodriguez
- [J5] 2014 IJRR *A Data-Driven Statistical Framework for Post-Grasp Manipulation*
Paolini, R., A. Rodriguez, S. Srinivasa and M. Mason
- [J4] 2012 IJRR *Autonomous Manipulation with a General-Purpose Simple Hand*
Mason, M., A. Rodriguez, S. Srinivasa and A. Vazquez
- [J3] 2012 IJRR *Grasp Invariance*
Rodriguez, A. and M. Mason
- [J2] 2012 TRO *Path-Connectivity of the Free Space*
Rodriguez, A. and M. Mason
- [J1] 2012 IJRR *From Caging to Grasping*
Rodriguez, A., M. Mason and S. Ferry

Refereed Conference Papers

- [C66] 2021 ICRA *Tactile-RL for Insertion: Generalization to Objects of Unknown Geometry*
Dong S., D. Jha, D. Romeres, S. Kim, D. Nikovski and A. Rodriguez
- [C65] 2021 ICRA *Planning for Multi-stage Forceful Manipulation*
Holladay R., T. Lozano-Perez and A. Rodriguez
- [C64] 2021 ICRA *Extrinsic Contact Sensing with Relative-Motion Tracking from Distributed Tactile Measurements*
Ma D., S. Dong, A. Rodriguez
- [C63] 2021 ICRA *Tactile SLAM: Real-time Inference of Shape and Pose from Planar Pushing*
Suresh A., M. Bauza, K-T. Yu, J. Mangelson, A. Rodriguez and M. Kaess
- [C62] 2021 ICRA *Robotic Grasping of Fully-Occluded Objects using RF Perception*
Boroushaki T., J. Leng, I. Clester, A. Rodriguez and F. Adib
- [C61] 2020 CoRL *Tactile Object Pose Estimation from First Touch with Geometric Contact Rendering*
Bauza M., E. Valls, B. Lim, T. Sechopoulos and A. Rodriguez
- [C60] 2020 CoRL *A Long Horizon Planning Framework for Manipulating Rigid Pointcloud Objects*

- [C59] 2020 IROS Simeonov A., Y. Du, B. Kim, F. Hogan, J. Tenenbaum, P. Agrawal and A. Rodriguez
PnuGrip: An Active Two-Phase Gripper for Dexterous Manipulation
- [C58] 2020 RSS Taylor I., N. Chavan-Dafle, G. Li, N. Doshi and A. Rodriguez
A Global Quasi-Dynamic Model for Contact-Trajectory Optimization
- [C57] 2020 RSS Aceituno-Cabezas B. and A. Rodriguez
Cable Manipulation with a Tactile-Reactive Gripper
She Y., S. Wang, S. Dong, N. Sunil, A. Rodriguez and E. Adelson
[RSS 2020 Best Paper Award Finalist](#)
- [C56] 2020 ICRA Accurate Vision-based Manipulation through Contact Reasoning
Kloss A., M. Bauza, J. Wu, J. Tenenbaum, A. Rodriguez and J. Bohg
- [C55] 2020 ICRA Long-Horizon Prediction and Uncertainty Propagation with Residual Point Contact Learners
Fazeli, N., A. Ajay, and A. Rodriguez
- [C54] 2020 ICRA Hybrid Differential Dynamic Programming for Planar Manipulation Primitives
Doshi, N., F. Hogan and A. Rodriguez
- [C53] 2020 ICRA Tactile Dexterity: Manipulation Primitives with Tactile Feedback
Hogan, F., J. Ballester, S. Dong and A. Rodriguez
[ICRA 2020 Best Manipulation Paper Award Finalist](#)
- [C52] 2019 ISRR Certified Grasping
Aceituno-Cabezas, B., J. Ballester, and A. Rodriguez
- [C51] 2019 IROS Force-and-Motion Constrained Planning for Tool Use
Holladay, R., T. Lozano-Perez and A. Rodriguez
- [C50] 2019 IROS Tactile-based Insertion for Dense Box-Packing
Dong, S. and A. Rodriguez
- [C49] 2019 IROS Omnipush: accurate, diverse, real-world dataset of pushing dynamics with RGB-D
Bauza, M., F. Alet, Y-C. Lin, T. Lozano-Perez, L. Kaelbling and A. Rodriguez
- [C48] 2019 IROS A Convex-Combinatorial Model for Planar Caging
Aceituno-Cabezas, B., H. Dai and A. Rodriguez
- [C47] 2019 ICML Graph Element Networks: adaptive, structured computation and memory
Alet, F., A. Jaks, M. Bauza, A. Rodriguez, T. Lozano-Perez and L. Kaelbling
- [C46] 2019 RSS TossingBot: Learning to Throw Arbitrary Objects with Residual Physics
Zeng, A., S. Song, J. Lee, A. Rodriguez and T. Funkhouser
[RSS 2019 Best System Paper Award](#)
- [C45] 2019 ICRA Tactile Mapping and Localization from High-Resolution Tactile Imprints
Bauza M., O. Canal and A. Rodriguez
- [C44] 2019 ICRA Dense Tactile Force Distribution Estimation using GelSlim and inverse FEM
Ma, D., E. Donlon, S. Dong and A. Rodriguez
- [C43] 2019 ICRA Maintaining Grasps within Slipping Bound by Monitoring Incipient Slip
Dong, S., D. Ma, E. Donlon and A. Rodriguez
- [C42] 2019 ICRA Combining Physical Simulators and Object-Based Networks for Control
Ajay, A., M. Bauza, J. Wu, N. Fazeli, J. Tenenbaum, A. Rodriguez and L. Kaelbling
- [C41] 2018 WAFR GP-SUM. Gaussian Process Filtering of non-Gaussian Beliefs
Bauza, M. and A. Rodriguez
- [C40] 2018 CoRL Data-Efficient Approach to Precise and Controlled Pushing
Bauze M., F. Hogan and A. Rodriguez
- [C39] 2018 IROS Augmenting Physical Simulators with Stochastic Neural Networks: Case Study of Planar Pushing and Bouncing
Ajay, A., J. Wu, N. Fazeli, M. Bauza, L. Kaelbling, J. Tenenbaum, and A. Rodriguez
[IROS 2018 Best Cognitive Paper Award](#)
- [C38] 2018 IROS Tactile Regrasp: Grasp Adjustments via Simulated Tactile Transformations
Hogan, F., M. Bauza, O. Canal, E. Donlon and A. Rodriguez
- [C37] 2018 IROS Realtime State Estimation with Tactile and Visual Sensing for Inserting a Suction-held Object
Yu, K.-T. and A. Rodriguez

- [C36] 2018 IROS *Learning Synergies between Pushing and Grasping with Self-supervised Deep Reinforcement Learning*
Zeng, A., S. Song, S. Welker, J. Lee, A. Rodriguez, and T. Funkhouser
[IROS 2018 Finalist Best Cognitive Paper Award](#)
- [C35] 2018 IROS *GelSlim: A High-Resolution, Compact, Robust, and Calibrated Tactile-sensing Finger*
Donlon, E., S. Dong, M. Liu, J. Li, E. Adelson and A. Rodriguez
[Finalist Amazon Best Technical Paper Award in Manipulation](#)
- [C34] 2018 CASE *Regrasping by Fixtureless Fixturing*
Chavan-Dafle N. and A. Rodriguez
- [C33] 2018 CASE *Pneumatic Shape-shifting Fingers to Reorient and Grasp*
Chavan-Dafle N., K. Lee and A. Rodriguez
- [C32] 2018 RSS *In-Hand Manipulation via Motion Cones*
Chavan-Dafle, N., R. Holladay and A. Rodriguez
[RSS 2018 Best Student Paper Award](#)
- [C31] 2018 ICRA *Stable Prehensile Pushing: In-Hand Manipulation with Alternating Sticking Contacts*
Chavan-Dafle, N. and A. Rodriguez
- [C30] 2018 ICRA *Realtime State Estimation with Tactile and Visual sensing. Planar Manipulation*
Yu, K.-T. and A. Rodriguez
- [C29] 2018 ICRA *Reactive Planar Manipulation with Convex Hybrid MPC*
Hogan, F., E. Romo and A. Rodriguez
- [C28] 2018 ICRA *Robotic Pick-and-Place of Novel Objects in Clutter with Multi-Affordance Grasping and Cross-Domain Image Matching*
Zeng, A., S. Song, K.-T. Yu, E. Donlon, F. Hogan, M. Bauza, D. Ma, O. Taylor, M. Liu, E. Romo, N. Fazeli, F. Alet, N. Chavan-Dafle, R. Holladay, I. Morona, P. Nair, D. Green, I. Taylor, W. Liu, T. Funkhouser and A. Rodriguez
[Amazon Best System Paper Award in Manipulation](#)
- [C27] 2017 ISRR *Fundamental Limitations in Performance and Interpretability of Common Planar Rigid-Body Contact Models*, Fazeli, N., S. Zapolsky, E. Drumwright and A. Rodriguez
- [C26] 2017 ISRR *Sampling-based Planning of In-Hand Manipulation with External Pushes*
Chavan-Dafle, N. and A. Rodriguez
- [C25] 2017 CoRL *Learning Data-Efficient Rigid-Body Contact Models: Case Study of Planar Impact*
Fazeli, N., S. Zapolsky, E. Drumwright and A. Rodriguez
- [C24] 2017 Human. *The Complexities of Grasping in the Wild*
Nakamura, Y., D. Troniak, A. Rodriguez, M. Mason and N. Pollard
- [C23] 2017 RSS *Optimal Shape and Motion Planning for Dynamic Planar Manipulation*
Taylor O. and A. Rodriguez
- [C22] 2017 ICRA *Empirical Evaluation of Common Impact Models on a Planar Impact Task*
Fazeli N., E. Donlon, E. Drumwright and A. Rodriguez A
- [C21] 2017 ICRA *A Probabilistic Data-Driven Model for Planar Pushing*
Bauza, M. and A. Rodriguez
- [C20] 2017 ICRA *Multi-view Self-supervised Deep Learning for 6D Pose Estimation in the Amazon Picking Challenge*
Zeng, A., K.T. Yu, S. Song, D. Suo, E. Walker Jr., A. Rodriguez, and J. Xiao
- [C19] 2016 WAFR *Feedback Control of the Pusher-Slider System: A Story Hybrid and Underactuated Contact Dynamics*
Hogan, F. and A. Rodriguez
- [C18] 2016 ISER *Experimental Validation of Contact Dynamic Models for In-hand Manipulation*
Kolbert, R., N. Chavan-Dafle and A. Rodriguez
- [C17] 2016 IROS *More than a Millions Ways to be Pushed. A Comprehensive and High-Fidelity Data Set of Planar Pushing*
Yu, K.T., M. Bauza, N. Fazeli and A. Rodriguez
[IROS 2016 Finalist Best Paper Award](#)
- [C16] 2015 ISRR *Identifiability Analysis of Rigid Body Frictional Contact*
N. Fazeli, R. Tedrake and A. Rodriguez

- [C15] 2015 IROS *Shape and Pose Recovery from Planar Pushing*
Yu, K.T., J. Leonard and A. Rodriguez
- [C14] 2015 IROS *A Novel Nonlinear Compliant Link on Simple Grippers*
Zhang, Z., A. Rodriguez and M. Mason
- [C13] 2015 IROS *Prehensile Pushing: In-hand Manipulation with Push-Primitives*
Chavan-Dafle, N. and A. Rodriguez
- [C12] 2015 CASE *A Two-Phase Gripper to Reorient and Grasp*
Chavan-Dafle, N., M. Mason, H. Staab, G. Rossano and A. Rodriguez
- [C11] 2014 ICRA *Extrinsic Dexterity: In-Hand Manipulation with External Forces*
Chavan-Dafle, N., A. Rodriguez, R. Paolini, B. Tang, S. Srinivasa, M. Erdmann, M. Mason, I. Lundberg, H. Staab and T. Fuhlbrigge
[ICRA 2014 Finalist Best Video Award](#)
- [C10] 2013 ICRA *A Simple and Compliant Force Sensing Palm for the MLab Simple Hand*
Zeglin, G., A. Rodriguez and M. Mason
- [C9] 2013 ICRA *Effector Form Design for 1DOF Planar Actuation*
Rodriguez, A. and M. Mason
[ICRA 2013 Best Student Paper Award](#)
- [C8] 2012 ISER *A Data-Driven Statistical Framework for Post-Grasp Manipulation*
Paolini, R., A. Rodriguez, S. Srinivasa, and M. Mason
- [C7] 2011 IROS *Abort and Retry in Grasping*
Rodriguez, A., M. Mason, S. Srinivasa, M. Bernstein and A. Zirbel
- [C6] 2011 RSS *From Caging to Grasping*
Rodriguez, A., M. Mason and S. Ferry
[RSS 211 Best Student Paper Award](#)
- [C5] 2010 ISER *Manipulation Capabilities with Simple Hands*
Rodriguez, A., M. Mason and S. Srinivasa
- [C4] 2010 WAFR *Grasp Invariance*
Rodriguez, A. and M. Mason
- [C3] 2010 CASE *Failure Detection in Assembly: Force Signature Analysis*
Rodriguez, A., D. Bourne, M. Mason, G. Rossano and J. Wang
- [C2] 2008 WAFR *Two Finger Caging: Squeezing and Stretching*
Rodriguez, A. and M. Mason
- [C1] 2007 ICINCO *RPQ: Robotic Proximity Queries. Development and Applications*
Hernansanz, A., X. Giral, A. Rodriguez and J. Amat

INVITED TALKS

“The Role of Manipulation Primitives in Building Dexterous Robotic Systems”

- 2021 Feb CMU, Robotics Institute Seminar, USA
2020 Dec MIT, Mechanical Engineering Colloquium, USA
2020 Dec Berkeley, DREAM/CPAR Seminar, USA

“From Crafting to Dexterous Robots”

- 2021 Feb MIT, Keynote at Laureates and Leaders induction ceremony, USA

“Good Practices for Good Writing”

- 2020 Jul RSS 2020, Workshop Good Citizens of Robotics Research

“Tactile-Driven Dexterity”

- 2020 Jul RSS 2020, Visuo-tactile Sensors for Robust Manipulation: From Perception to Control
2020 May ICRA 2020, ViTac: Closing the Perception-Action Loop with Vision and Tactile
2020 May ICRA 2020, Workshop on Learning of Manual Skills in Humans and Robots
2020 Apr ILP - Autonomy Symposium, MIT, USA
2019 Nov IROS 2019, Workshop RoboTac, Macao

“Robot Automation. Why is Robotic Grasping not a Solved Problem?”

- 2019 Nov Canon, ILP, Executive Briefing, MIT, USA
- 2019 Aug ABInBev Tech Training Workshop, New York, USA
- 2019 Jun Seminar in Digital Transformation, RCC Harvard, USA

“Certified Grasping”

- 2019 Nov IROS 2019, Workshop Manipulation Through Contacts, Macao

“A Vision for Tactile Dexterity and Reactive Manipulation”

- 2019 Oct Humanoids 2019, Workshop Humanoid Grasping and Manipulation, Toronto, Canada
- 2019 Oct Amazon Research Awards Symposium, Boston, USA
- 2019 Sep SENSE.nano Symposium, MIT, USA
- 2019 Sep Mitsubishi Electric Research Laboratories, Cambridge, USA
- 2019 Jun Lincoln Labs, USA
- 2019 Jun Workshop on Adaptive Control, Learning, and Robotics, Yale, USA
- 2019 Jun Mathworks, USA
- 2019 May ICRA 2019, Workshop on Integrating Vision and Touch, Montreal, Canada
- 2019 Apr Robotics Jam Sessions, University of Pisa, Italy

“Manipulation Skills that I Wish my Robots Had”

- 2019 Oct Boston Dynamics, Waltham, USA
- 2019 Apr KTH, Rootics Seminar, Stockholm, Sweden
- 2018 Oct MIT, Mechanical Engineering Colloquium, USA
- 2018 Oct Keynote at IROS 2018, Madrid, Spain
- 2018 Aug Keynote at World Robot Conference, Beijing, China
- 2018 May MIT, Mechanical Engineering Department Area Seminar, USA
- 2018 Feb Berkeley, Peoples and Robots Seminar, USA
- 2018 Jan HKUST, Robotics Institute Seminar, Hong Kong
- 2017 Oct NERC 2017, Northeastern University, Boston, USA
- 2017 Sep IROS 2017, Workshop on Contact Frontiers, Vancouver, Canada

“Why Do We Like Benchmarks?”

- 2019 Aug Facebook Workshop on Benchmarks in Robotics, Pittsburgh, USA

“Robot Manipulation Planning: A Hierarchy of Problems to Solve and Decisions to Make”

- 2019 Jun RSS 2019, Workshop on Learning vs. Reasoning, Freiburg, Germany

“Robotic Dexterous Picking”

- 2019 Jan ILP Symposium, Shenzhen, China
- 2019 Jan SUSTech, Shenzhen, China
- 2018 Nov ILP Symposium, MITSUI, Boston, USA

“Embrace Frictional Contact in Manipulation”

- 2018 Dec Boston Dynamics, Waltham, USA

“Adventures on Tactile Sensing”

- 2018 Oct Amazon Grant Symposium, Boston, USA.
- 2018 May ICRA 2018, Workshop Active Touch for Perception and Interaction, Australia
- 2017 Jul RSS 2017, Workshop Tactile Sensing for Manipulation, Cambridge, USA

“Fundamentals of Robotic Manipulation”

- 2018 Jul Summer School on Cognitive Robotics, Cambridge, USA
- 2017 Jul Summer School on Soft Robotics, Lake Chiemsee, Germany
- 2017 Jun Summer School on Cognitive Robotics, Cambridge, USA

"Affordances for Picking, Pushing, and their Synergies"

2018 Jun RSS 2018, Workshop on Computational Models of Affordance, PA, USA

"Reactive Robotic Manipulation"

2017 Jul RSS 2017, Workshop Contact - Turning a problem into a solution, Cambridge, USA

2017 May ICRA 2017, Workshop Sensor-based Object Manipulation for Assembly, Singapore

2017 May University of Washington, Robotics Colloquia, Seattle, USA

2017 May MIT, School of Engineering, Junior faculty luncheon, Cambridge, USA

"Team MIT-Princeton's Approach to the Amazon Robotics Challenge"

2018 Jun ABB Inc. US Corporate Research Center, Bloomfield, CT, USA

2018 May ICRA 2018, Workshop Advances in Robot Warehouse Automation.

2018 Jan MIT, Mechanical Engineering Department Faculty Retreat, USA

2017 May ICRA Workshop Warehouse Picking Automation, Singapore

2016 Jul ABB Inc. US Corporate Research Center, Bloomfield, CT, USA

"Dexterous Manipulation with non-Dexterous Manipulators"

2017 Jun ICRA 2017, Workshop AI in Automation, Singapore

2016 Oct IROS 2016, Workshop Dexterity acquisition in object manipulation, Daejeon, S. Korea

2016 May ABB Inc. Corporate Research Center, Vasteras, Sweden

2016 May ICRA 2016, Workshop Contact and Dynamics in Manipulation, Stockholm, Sweden

2016 Mar Northwestern University, NxR Lab, Evanston, USA

2015 Oct TATA Consultancy Services, Noida, India.

2015 Aug MIT, LIDS, Summer Dynamics and Information Lunches, Boston, USA

2015 Jul Delta Corporation, Taipei, Taiwan

2015 Jul EPOCH Symposium - The Future of Robotics and Machine Learning, Taipei, Taiwan

2015 Jul EPOCH Foundation, Garage+, Taipei, Taiwan

2014 Apr Locomotion Group, MIT-CSAIL, Boston, USA

"Experiments with Frictional Contact"

2016 Dec SIMPAR 2016, Workshop Grand Challenges in Robot Simulation, San Francisco, USA

"The Pusher-Slider: A Story of Hybrid and Underactuated Contact Dynamics"

2016 Oct IROS 2016, Workshop Closed-loop Object Manipulation, Daejeon, S. Korea

2016 Oct MIT Robotics Seminar, Cambridge, USA

2016 Oct Mathworks, Natick, USA

"Robots in a low labor cost economy"

2015 Oct TATA Consultancy Services, Noida, India

2015 Oct MIT Alumni Club, Pune, India

2015 Oct NASSCOM Engineering Summit, Keynote, Pune, India

"Prehensile Pushing: In-hand Manipulation with External Forces"

2015 May ICRA 2015, Workshop Robotic Hands, Grasping, and Manipulation, Seattle, USA

"Primer on Manipulation"

2014 Apr MIT, Mechanical Engineering, Course 2.165 Robotics, Boston, USA

"Shape for Contact"

2013 Sep Massachusetts Institute of Technology, CSAIL, Locomotion Group, Boston, USA

2013 Jul Carnegie Mellon University, CFR Seminar, Robotics Institute, CMU, Pittsburgh, USA

"Contacting the World with Mechanical and Data-Driven Intelligence"

2014 Apr WPI, Computer Science, Worcester, USA
2014 Mar MIT, Mechanical Engineering, Graduate program Open House, Boston, USA
2013 Apr Georgia Tech, School of Interactive Computing, Atlanta, USA
2013 Mar MIT, Mechanical Engineering, Boston, USA
2013 Mar UMASS, Computer Science, Amherst, USA
2013 Mar Stanford, Computer Science, Stanford, USA
2013 Mar University of Maryland, Mechanical Engineering, College Park, USA
2013 Feb USC, Department of Computer Science, Los Angeles, USA

“Data-Driven Manipulation with a Simple Hand”

2012 Nov Georgia Tech, RIM Center, Atlanta, USA

“Grasp Invariance”

2011 Feb LAAS-CNRS, Toulouse, France
2010 Nov CMU, CFR Seminar, Pittsburgh, USA

“From Caging to Grasping”

2011 Jun RSS 2011, Full oral presentation, Los Angeles, USA
2011 May ICRA 2011 Workshop “Uncertainty in Automation”, Shanghai, China
2008 May CMU, Human Sensing Laboratory, Pittsburgh, USA
2006 Dec UPC, ESAII, Barcelona, Spain